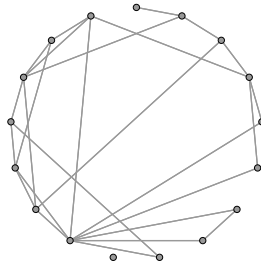
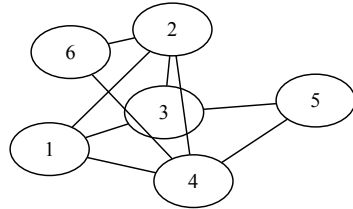
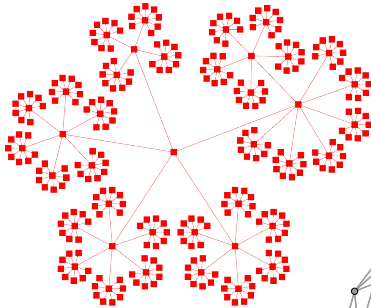


Evaluation of Graph Drawings as Embeddings for Routing in Distributed Systems



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Introduction

Graph drawing algorithms

- Circular drawing algorithms

- Hierarchical drawing algorithms

- Force-driven drawing algorithms

Routing algorithms

Evaluation

- Graph types

- Root vertex choice

- Routing in Barabási-Albert graphs

- Runtimes and routing success

Conclusion and future work

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Routing in distributed systems

Introduction

- ▶ Routing in a distributed system requires an identifier space

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- ▶ Routing in a distributed system requires an identifier space
 - ▶ Assignment of coordinates to each node in the system

Routing in distributed systems

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- ▶ Routing is done with local knowledge only

Routing in distributed systems

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 - ▶ Assignment of coordinates to each node in the system
- ▶ Routing is done with local knowledge only
 - ▶ Coordinates of sender and destination node are known

Routing in distributed systems

Introduction

- ▶ Routing in a distributed system requires an identifier space
 - ▶ Assignment of coordinates to each node in the system
- ▶ Routing is done with local knowledge only
 - ▶ Coordinates of sender and destination node are known
 - ▶ Each node knows its neighbors coordinates

Routing in distributed systems

Existing algorithms: CAN



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- ▶ **C**ontent-**A**ddressable **N**etwork

Routing in distributed systems

Existing algorithms: CAN



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Routing in distributed systems

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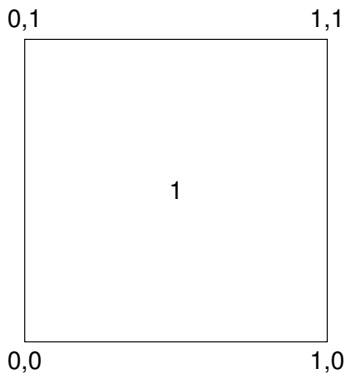
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- ▶ The joining node will built up connections to its neighbors
- ▶ Greedy routing is enabled by design and always successful

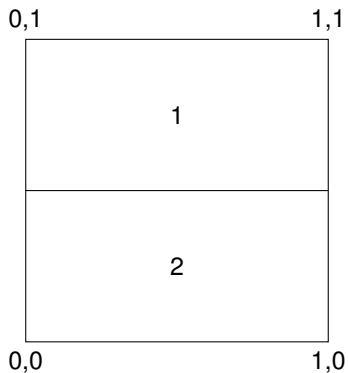
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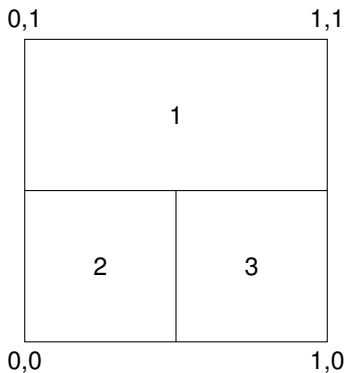
Routing in distributed systems

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Routing in distributed systems

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Scenario: routing in distributed systems

Preconditions for our work



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- ▶ A network is given, with all vertices and edges

Scenario: routing in distributed systems

Preconditions for our work

- ▶ A network is given, with all vertices and edges
 - ▶ Friend-to-friend networks / Darknets

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 - ▶ Friend-to-friend networks / Darknets
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- ▶ No vertices or edges must be left out or added

Scenario: routing in distributed systems

Preconditions for our work

- ▶ A network is given, with all vertices and edges
 - ▶ Friend-to-friend networks / Darknets
- ▶ Routing should be made possible
- ▶ No vertices or edges must be left out or added
 - ▶ Contrast to DHTs: assume the graph structure to be strictly fixed

Scenario: routing in distributed systems

Preconditions for our work



1:8252;18292;19951;21024;17656

2:8655;12237;12497;14863

3:2370;2483;4111;5781;16632;23896

4:7739;10140;10342;12794;14266

5:4010;5545;13193;17423

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Scenario: routing in distributed systems

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Scenario: routing in distributed systems

Our approach



- ▶ Use graph drawing algorithms as an embedding to assign a coordinate space

Scenario: routing in distributed systems

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Scenario: routing in distributed systems

Our approach

- ▶ Use graph drawing algorithms as an embedding to assign a coordinate space
- ▶ Distributed greedy routing algorithms can be used now
 - ▶ No need to construct large routing tables
 - ▶ Each vertex only knows its neighbors and their coordinates

Introduction

Graph drawing algorithms

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Graph drawing algorithms

Classification

- ▶ Fixed-vertex drawing algorithms

Graph drawing algorithms

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- ▶ Fixed-vertex drawing algorithms
 - ▶ Choose a layout (straight line, circular, ...)

Graph drawing algorithms

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- ▶ Fixed-vertex drawing algorithms
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 - ▶ Tree-like layout

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- ▶ Force-driven drawing algorithms

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 - ▶ Simulate a physical model

Graph drawing algorithms

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 - ▶ Tree-like layout
 - ▶ Either vertically arranged (root vertex at the top) . . .
 - ▶ . . . or circularly arranged (root vertex in the middle)
 - ▶ Result: two-dimensional identifier space
- ▶ Force-driven drawing algorithms
 - ▶ Simulate a physical model
 - ▶ Result: n-dimensional identifier space

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- ▶ Return a circular arrangement of vertices

Algorithm by Six and Tollis



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- ▶ Return a circular arrangement of vertices
- ▶ Minimize the number of edge crossings

Algorithm by Six and Tollis

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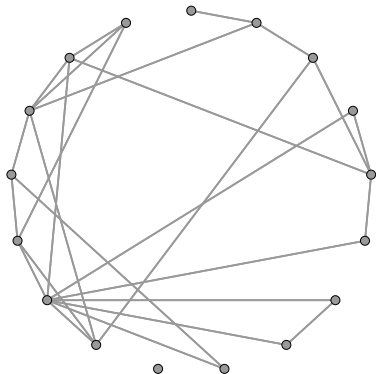
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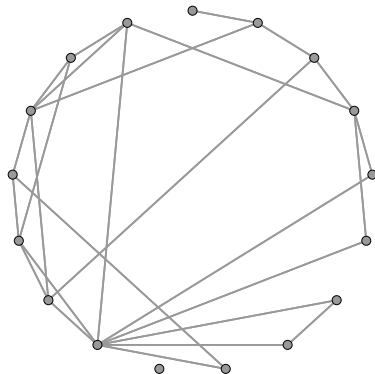
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- ▶ Split up the work into two phases
 - ▶ First phase: use a complex algorithm to get a layout with (relatively) little crossings
 - ▶ Place as much edges as possible on the circumference
 - ▶ Second phase: swap neighbors to further reduce crossings

Algorithm by Six and Tollis

Example drawings



After first phase



Final layout

Algorithm by Six and Tollis

Summary



- ▶ Algorithm returns aesthetically pleasing results on low-degree graphs

Algorithm by Six and Tollis

Summary

- ▶ Algorithm returns aesthetically pleasing results on low-degree graphs
- ▶ Very sophisticated and complex algorithm

Algorithm by Six and Tollis

Summary

- ▶ Algorithm returns aesthetically pleasing results on low-degree graphs
- ▶ Very sophisticated and complex algorithm
- ▶ But: as the average degree and the number of vertices grows, the algorithm gets horribly slow

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- ▶ Return a tree-like arrangement of vertices with a root vertex at the top

Algorithm by Wetherell and Shannon



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- ▶ Return a tree-like arrangement of vertices with a root vertex at the top
- ▶ Initially: choose any vertex as the root

Algorithm by Wetherell and Shannon



- ▶ Return a tree-like arrangement of vertices with a root vertex at the top
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- ▶ Transform the graph to a spanning tree

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- ▶ Initially: choose any vertex as the root
- ▶ Transform the graph to a spanning tree
- ▶ Algorithm traverses the spanning tree twice
 - ▶ First time for relative positioning of each vertex to its parent vertex in the tree
 - ▶ Second time for absolute positioning

- ▶ Return a hierarchical arrangement of vertices with a root vertex at the center

Algorithm by Melançon and Herman



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- ▶ Return a hierarchical arrangement of vertices with a root vertex at the center
- ▶ Initially: create a spanning tree

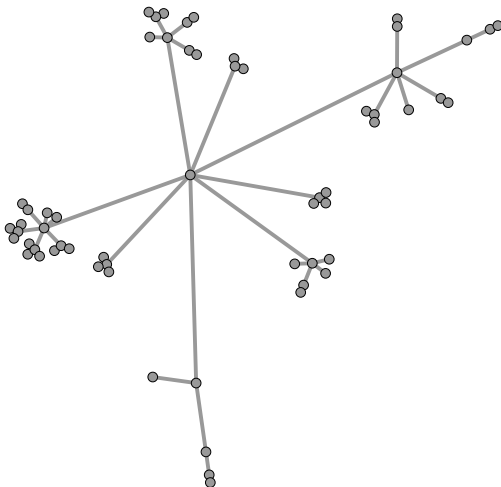
Algorithm by Melançon and Herman

- ▶ Return a hierarchical arrangement of vertices with a root vertex at the center
- ▶ Initially: create a spanning tree
- ▶ Child vertices are arranged on a circle around their common parent vertex

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- ▶ Initially: create a spanning tree
- ▶ Child vertices are arranged on a circle around their common parent vertex
- ▶ Radii are decreased exponentially to avoid overlapping

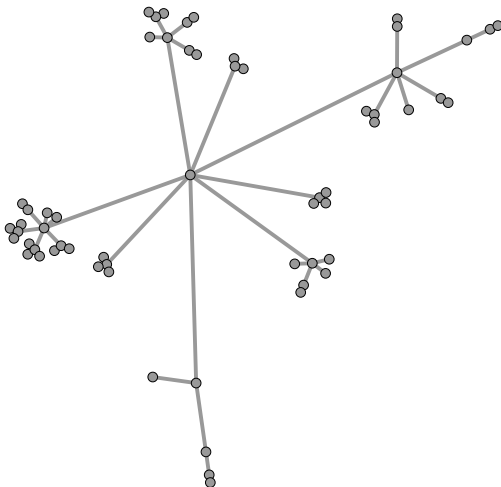
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Example drawing



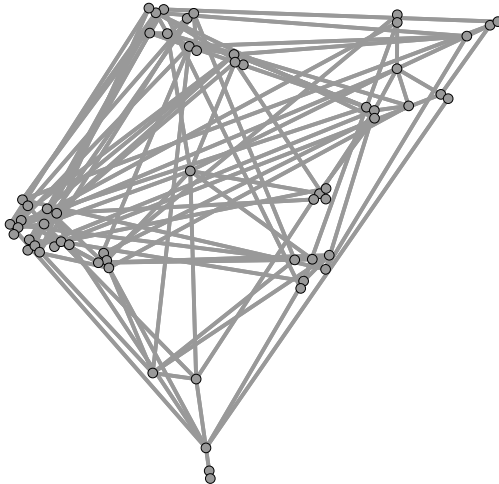
Algorithm by Melançon and Herman

Example drawing - spanning tree



Algorithm by Melançon and Herman

Example drawing - complete graph



Hierarchical drawing algorithms

Summary

- ▶ Huge advantage of these algorithms: fast results

Hierarchical drawing algorithms

Summary

- ▶ Huge advantage of these algorithms: fast results
- ▶ Drawings cannot visualize the structure of cyclic graphs

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Force-driven drawing algorithm by Fruchterman and Reingold



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-
- ▶ Return an arrangement of evenly distributed vertices

Force-driven drawing algorithm by Fruchterman and Reingold



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-
- ▶ Return an arrangement of evenly distributed vertices
 - ▶ Clusters can easily be identified

Force-driven drawing algorithm by Fruchterman and Reingold



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- ▶ Return an arrangement of evenly distributed vertices
 - ▶ Clusters can easily be identified
 - ▶ Represent vertices by steel rings and edges by springs

Force-driven drawing algorithm by Fruchterman and Reingold



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- ▶ Return an arrangement of evenly distributed vertices
- ▶ Clusters can easily be identified
- ▶ Represent vertices by steel rings and edges by springs
- ▶ Take any random initial position for the vertices

Force-driven drawing algorithm by Fruchterman and Reingold



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- ▶ Return an arrangement of evenly distributed vertices
- ▶ Clusters can easily be identified
- ▶ Represent vertices by steel rings and edges by springs
- ▶ Take any random initial position for the vertices
- ▶ Release the rings and let them swing into an optimal state

Force-driven drawing algorithm by Fruchterman and Reingold



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 - ▶ Adjacent vertices should appeal each other

Force-driven drawing algorithm by Fruchterman and Reingold



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Force-driven drawing algorithm by Fruchterman and Reingold



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- ▶ Iterative algorithm

Force-driven drawing algorithm by Fruchterman and Reingold

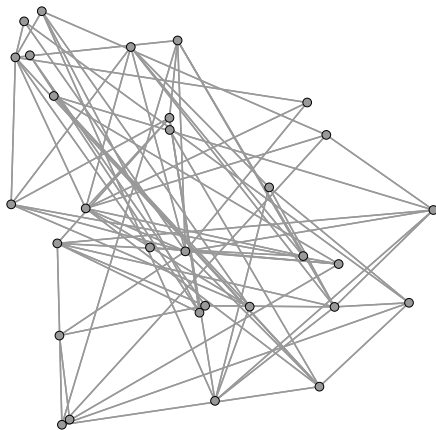


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- ▶ Release the rings and let them swing into an optimal state
 - ▶ Adjacent vertices should appeal each other
 - ▶ Nonadjacent vertices should repel each other
- ▶ Iterative algorithm
 - ▶ May take ten or thousand iterations until a “stable” position is reached

Force-driven drawing algorithm by Fruchterman and Reingold

Example drawing: initial positioning

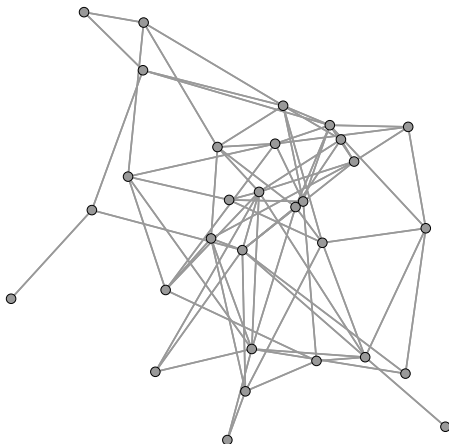


Force-driven drawing algorithm by Fruchterman and Reingold

Example drawing: after 50 iterations

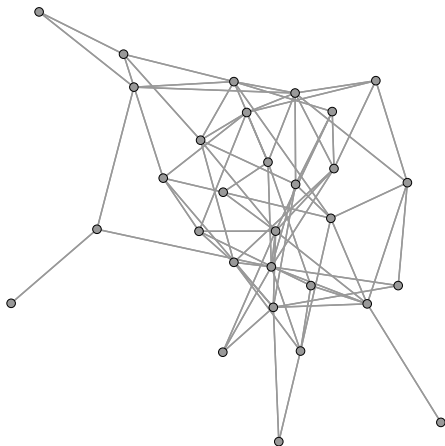


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Force-driven drawing algorithm by Fruchterman and Reingold

Example drawing: after 150 iterations



Force-driven drawing algorithm by Fruchterman and Reingold

Summary



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- ▶ Versatile algorithm for all kinds of graphs

Force-driven drawing algorithm by Fruchterman and Reingold

Summary



TECHNISCHE
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- ▶ Versatile algorithm for all kinds of graphs
- ▶ Problem: missing termination check

Force-driven drawing algorithm by Fruchterman and Reingold

Summary



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- ▶ Versatile algorithm for all kinds of graphs
- ▶ Problem: missing termination check
 - ▶ Stable state reached after ten or a hundred iterations?

Force-driven drawing algorithm by Fruchterman and Reingold

Summary



- ▶ Versatile algorithm for all kinds of graphs
- ▶ Problem: missing termination check
 - ▶ Stable state reached after ten or a hundred iterations?
- ▶ Common runtime for each iteration step roughly $\Theta(|V| + |E|^2)$

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Greedy routing

- ▶ In each routing step:



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- ▶ Characteristics in the usage (based on a random embedding)

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 - ▶ Very fast computation (< 1 ms per route)



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 - ▶ Terminate if either the destination is reached (routing success) or the distance cannot be decreased anymore (routing failure)
- ▶ Characteristics in the usage (based on a random embedding)
 - ▶ Very fast computation (< 1 ms per route)
 - ▶ Mostly short routes (< 6 hops, even in large graphs)



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 - ▶ Calculate the distances from each neighbor vertex of the current vertex to the destination
 - ▶ Continue routing at the hop with closest distance
 - ▶ Terminate if either the destination is reached (routing success) or the distance cannot be decreased anymore (routing failure)
- ▶ Characteristics in the usage (based on a random embedding)
 - ▶ Very fast computation (< 1 ms per route)
 - ▶ Mostly short routes (< 6 hops, even in large graphs)
 - ▶ Low average success rate (usually $< 10\%$)

Greedy routing with backtracking

- ▶ Enhancement to greedy routing: if a dead end was found, continue the route at the prior hop

Greedy routing with backtracking

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- ▶ Final routes also contain these indirect paths

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- ▶ Characteristics in the usage
 - ▶ Relatively slow computation ($< 40\text{ms}$ per route)
 - ▶ Short routes (average < 4 hops, maximum up to 12 hops)
 - ▶ Medium average success rate (up to 10% in random graphs, up to 60% in real-world scale-free networks)



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- ▶ Graphs based on the Erdős-Rényi model

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- ▶ Graphs based on the Erdős-Rényi model
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Graph types used for the evaluation



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Graph types used for the evaluation



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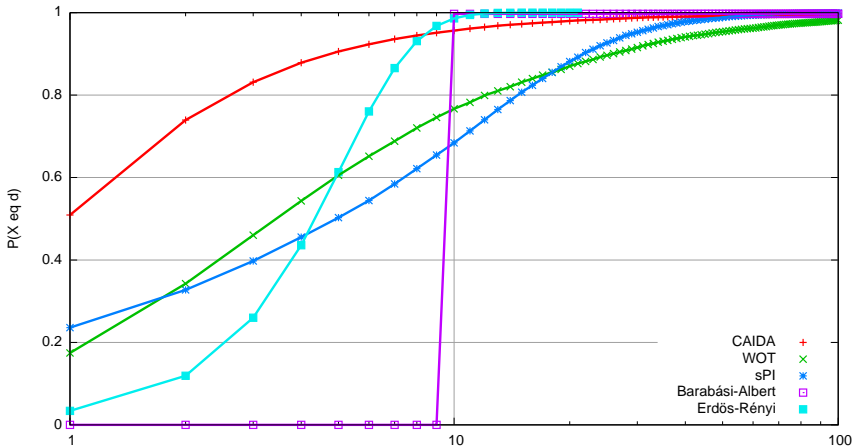


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 - ▶ The OpenPGP Web of Trust, another social network

Graph types used for the evaluation

Degree distribution



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Influence of the root vertex choice in hierarchical drawing algorithms

- ▶ Hierarchical drawing algorithms work on a spanning tree

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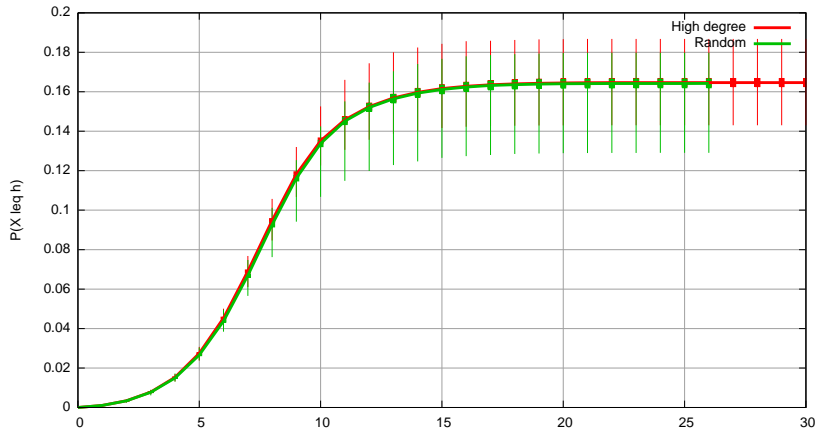
Influence of the root vertex choice in hierarchical drawing algorithms

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 - ▶ Some vertex with relatively high degree?

Influence of the root vertex choice in hierarchical drawing algorithms

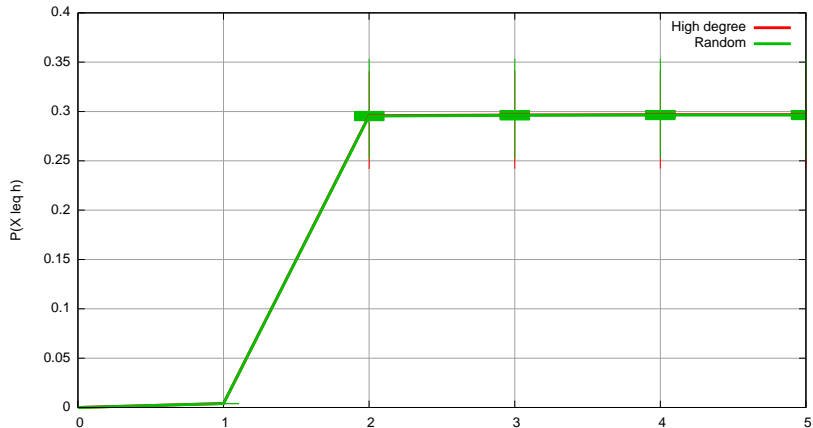
- ▶ Hierarchical drawing algorithms work on a spanning tree
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 - ▶ Some vertex with relatively high degree?
 - ▶ Random vertex?

Influence of the root vertex choice in hierarchical drawing algorithms



Erdős-Rényi graph with 5,000 vertices, embedded using Melançon/Herman

Influence of the root vertex choice in hierarchical drawing algorithms



Barabási-Albert with 5,000 vertices, embedded using Wetherell/Shannon

Influence of the root vertex choice in hierarchical drawing algorithms



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- ▶ Similar results using other graph types and hierarchical embeddings

Influence of the root vertex choice in hierarchical drawing algorithms

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Influence of the root vertex choice in hierarchical drawing algorithms

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- ▶ . . . in other cases, a drawing using a vertex with high degree as the root leads to “better” results
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- ▶ Root vertex choice does not influence the routing results

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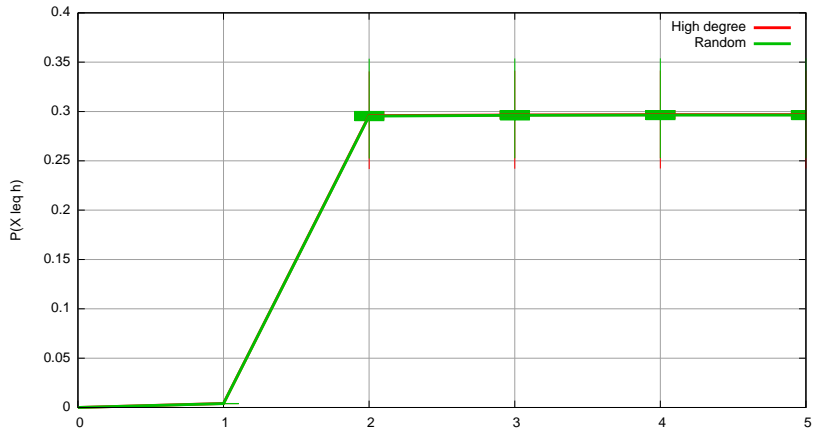
Root vertex choice

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Routing in Barabási-Albert graphs



Barabási-Albert with 5,000 vertices, embedded using Wetherell/Shannon



- ▶ Little number of routes succeed after one hop

Routing in Barabási-Albert graphs



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- ▶ Little number of routes succeed after one hop
- ▶ Majority of routes succeed with two hops



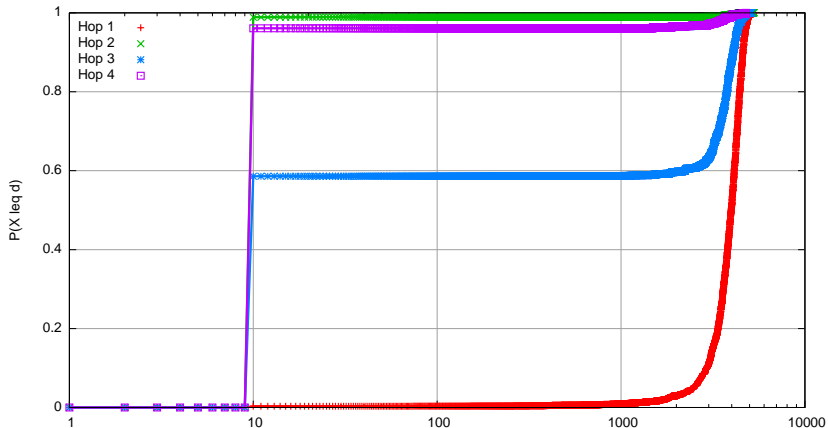
- ▶ Little number of routes succeed after one hop
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- ▶ Little number of routes succeed after one hop
- ▶ Majority of routes succeed with two hops
- ▶ Little number of routes takes more than two hops

- ▶ Hypothesis: Routing on Barabási-Albert graphs either succeeds after two hops or fails

Routing in Barabási-Albert graphs



Hop degree distribution in greedy routing on Barabási-Albert graphs

Routing in Barabási-Albert graphs



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- ▶ First hop: any high degree vertex



- ▶ First hop: any high degree vertex
 - ▶ Only seldom the destination



- ▶ First hop: any high degree vertex
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 - ▶ But: has many connections
 - ▶ Might also have an edge to the destination vertex?



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 - ▶ But: has many connections
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- ▶ Second hop: any low degree vertex

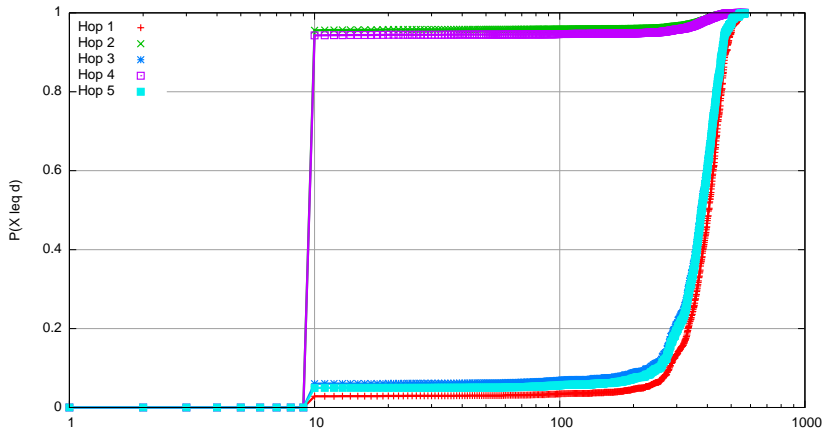
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 - ▶ Majority of vertices in a BA graph have a relatively low degree

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Routing in Barabási-Albert graphs



Hop degree distribution in greedy routing with backtracking

Routing in Barabási-Albert graphs

Summary

- ▶ Routing on Barabási-Albert graphs either succeeds after two hops or fails

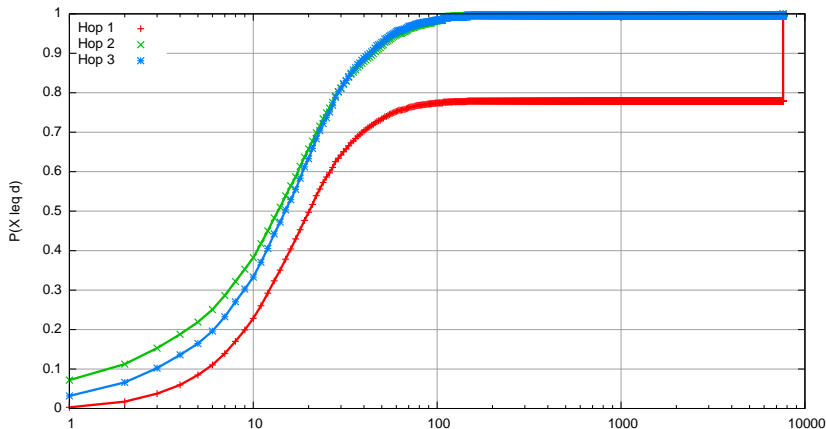
Routing in Barabási-Albert graphs

Summary



- ▶ Routing on Barabási-Albert graphs either succeeds after two hops or fails
- ▶ Choosing “wrong” first hop cannot be recovered!

Routing in Barabási-Albert graphs



Hop degree distribution in greedy routing on the sPI network

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- ▶ Six/Tollis

Runtimes of the evaluated graph drawing algorithms



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 - ▶ 5sec on an Erdős-Rényi graph with 1,000 vertices and 5,000 edges

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 - ▶ < 25msec on the scale-free graph extracted from the *Web of trust*
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 - ▶ 36sec on an Erdős-Rényi graph with given size

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 - ▶ < 25msec on the scale-free graph extracted from the *Web of trust*
- ▶ Fruchterman/Reingold
 - ▶ 36sec on an Erdős-Rényi graph with given size
 - ▶ 17min on an Barabási-Albert graph with given size

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 - ▶ 36sec on an Erdős-Rényi graph with given size
 - ▶ 17min on an Barabási-Albert graph with given size
 - ▶ > 13h on the scale-free graph extracted from the *Web of trust*

Routing success of the evaluated graph drawing algorithms



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Routing success of the evaluated graph drawing algorithms



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Routing success of the evaluated graph drawing algorithms

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 - ▶ WS: less than 2% using greedy routing, MH: up to 13%

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- ▶ Wetherell/Shannon and Melançon/Herman
 - ▶ WS: less than 2% using greedy routing, MH: up to 13%
 - ▶ WS: less than 5% using greedy routing with backtracking, MH: about 60%

Routing success of the evaluated graph drawing algorithms

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 - ▶ More than 70% routing success using lookahead routing (ttl 50 hops)
- ▶ Wetherell/Shannon and Melançon/Herman
 - ▶ WS: less than 2% using greedy routing, MH: up to 13%
 - ▶ WS: less than 5% using greedy routing with backtracking, MH: about 60%
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Routing success of the evaluated graph drawing algorithms

- ▶ Following results based on an Erdős-Rényi graph with 10,000 vertices and 50,000 edges
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 - ▶ Less than 20% using lookahead routing

Routing success of the evaluated graph drawing algorithms



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- ▶ Six/Tollis: Long-running algorithm in larger graphs

Routing success of the evaluated graph drawing algorithms



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Routing success of the evaluated graph drawing algorithms



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- ▶ Six/Tollis: Long-running algorithm in larger graphs
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Routing success of the evaluated graph drawing algorithms



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- ▶ Six/Tollis: Long-running algorithm in larger graphs
- ▶ Melançon/Herman: Very fast algorithm
- ▶ Routing results comparable
- ▶ No obvious recommendation possible

Introduction

Graph drawing algorithms

- Circular drawing algorithms

- Hierarchical drawing algorithms

- Force-driven drawing algorithms

Routing algorithms

Evaluation

- Graph types

- Root vertex choice

- Routing in Barabási-Albert graphs

- Runtimes and routing success

Conclusion and future work

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- ▶ Evaluation of graph drawings as embeddings for routing in distributed systems

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- ▶ Literature research about graph drawing algorithms and selection
- ▶ Implementation of graph drawing algorithms
- ▶ Simulation and evaluation of routing success
- ▶ Graph drawing algorithms **can** be used as embeddings

-
- ▶ Other spanning tree choices for hierarchical drawing algorithms

Future work

- ▶ Other spanning tree choices for hierarchical drawing algorithms
- ▶ Improved termination conditions for Six/Tollis or Fruchterman/Reingold



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Evaluation of Graph Drawings as Embeddings for Routing in Distributed Systems



Thanks for your attention!